

FEATURES

High accuracy, less than 0.1% error over a dynamic range of 500 : 1

Exactly measure the real power in the positive orientation and negative orientation, calculate the energy in the same orientation

A PGA in the current channel allows using small value shunt and burden resistance

The low frequency outputs F1 and F2 can directly drive electromechanical counters and two phase stepper motors and the high frequency output CF, supplies instantaneous real power, is intended for calibration and communications

The logic outputs REVP can be used to indicate a potential orientation

Low static power (typical value of 15mW). The technology of SLiM (Smart-Low-current-Management) is used.

On-Chip power supply detector

On-Chip anti-creep protection

On-Chip voltage reference of $2.42V \pm 8\%$ (typical temperature coefficient of $30\text{ppm}/^\circ\text{C}$), with external overdrive capability

Single 5V supply

Credible work, working time is more than twenty years

Interrelated patents are pending

DESCRIPTION

The is a low cost, high accuracy, high stability, simple peripheral circuit electrical energy meter IC. The meter based on the is intended for using in single-phase, two-wire distribution systems.

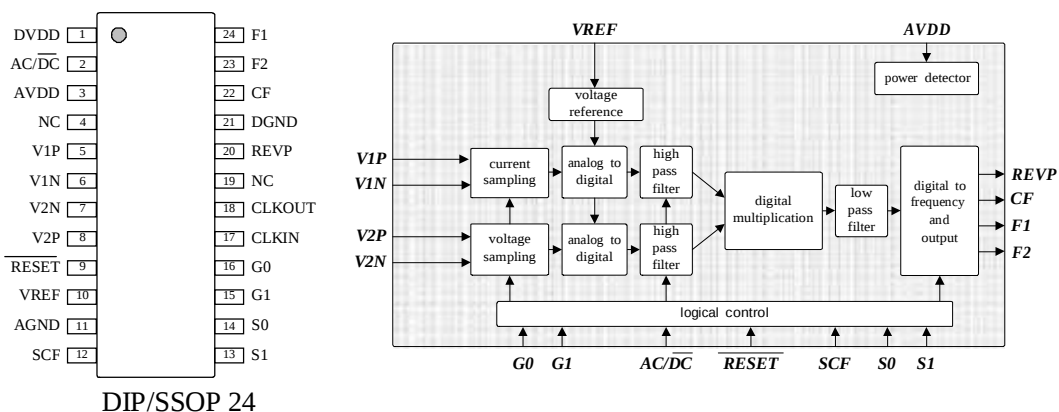
The adopts the oversample technology and digital signal processing technology. It can exactly measure the real power in the positive orientation and negative orientation and calculate the energy in the same orientation. Moreover, supplies the negative orientation indication on Pin20 (REVP). Therefore, the meter using the has great capability to avoid fault condition.

The supplies average real power information on the low frequency outputs F1 (Pin23) and F2 (Pin24). These logic outputs may be used to directly drive an electromechanical counter and two-phase stepper motors. The CF (Pin22) logic output gives instantaneous real power information. This output is intended to be used for calibration purposes or interface to an MCU.

Th adopts the technology of SLim and decreases greatly the static power. This technology also decreases the request for power supply.

The stability of reading error in the process of calibration. An internal no-load threshold ensures that the does not exhibit any creep when there is no load.

BLOCK DIAGRAM



PIN DESCRIPTIONS

Pin	Symbol	DESCRIPTIONS
1	DVDD	Digital Power Supply (+5V). Provides the supply voltage for the digital circuitry. It should be maintained at $5\text{ V} \pm 5\%$ for specified operation.
2	AC/DC	High-Pass Filter Select. This logic input is used to enable the high pass filter in the current channel. Logic high on this pin enables the HPF.
3	AVDD	Analog Power Supply (+5V). Provides the supply voltage for the analog circuitry. It should be maintained at $5\text{ V} \pm 5\%$ for specified operation.
4	NC	Reserved.
5,6	V1P,V1N	Inputs for Current Channel. These inputs are fully differential voltage inputs with a maximum signal level of $\pm 660\text{ mV}$
7,8	V2N,V2P	Negative and Positive Inputs for Voltage Channel. These inputs provide a fully differential input pair. The maximum differential input voltage is $\pm 660\text{ mV}$ for specified operation.
9	RESET	Reset Pin. Logic low on this pin will hold the ADCs and digital circuitry in a reset condition and clear internal registers.
10	VREF	On-Chip Voltage Reference. The on-chip reference has a nominal value of $2.5\text{V} \pm 8\%$ and a typical temperature coefficient of $30\text{ppm}/^\circ\text{C}$. An external reference source may also be connected at this pin.
11	AGND	Analog Ground Reference. Provides the ground reference for the analog circuitry.
12	SCF	Calibration Frequency Select. This logic input is used to select the frequency on the calibration output CF.
13,14	S1,S0	Output Frequency Select. These logic inputs are used to select one of four possible frequencies for the digital-to-frequency conversion. This offers the designer greater flexibility when designing the energy meter.
15,16	G1,G0	Gain Select. These logic inputs are used to select one of four possible gains for current channel. The possible gains are 1, 2, 8, and 16.
17	CLKIN	Clock In. An external clock can be provided at this logic input. Alternatively, a crystal can be connected across this pin and pin18 (CLKOUT) to provide a clock source
18	CLKOUT	Clock Out. A crystal can be connected across this pin and pin17 (CLKIN) as described above to provide a clock source.
19	NC	Reserved.
20	REVP	Negative Indication. Logic high indicates negative power, i.e., when the phase angle between the voltage and current signals is greater than 90° . This output is not latched and will be reset when positive power is once again detected.
21	DGND	Digital Ground Reference. Provides the ground reference for the digital circuitry.
22	CF	Calibration Frequency. The CF logic output gives instantaneous real power information. This output is intended to use for calibration purposes.
23,24	F1,F2	Low-Frequency. F1 and F2 supply average real power information. The logic outputs can be used to directly drive electromechanical counters and 2-phase stepper motors.

ABSOLUTE MAXIMUM RATINGS

(T = 25 °C)

Parameter	Symbol	Value	Unit
Analog Power Voltage AVDD	AVDD	-0.3~+7(max)	V
Digital power Voltage DVDD	DVDD	-0.3~+7(max)	V
DVDD to AVDD		-0.3~+0.3	V
Analog Input Voltage of Channel 2 to AGND	V (V)	$V_{SS}+0.5 \leq V(v) \leq V_{DD}-0.5$	V
Analog Input Voltage of Channel 1 to AGND	V (I)	$V_{SS}+0.5 \leq V(i) \leq V_{DD}-0.5$	V
Operating Temperature Range	Topr	-40~+85	°C
Storage Temperature Range	Tstr	-55~+150	°C
Power Dissipation (DIP24)		400	mW

Electronic Characteristic Parameter

(T=25°C, AVDD=5V, DVDD= 5V, CLKIN=3.58MHz)

Parameter	Symbol	Test Condition	Measure Pin	Min Value	Typical Value	Max Value	Unit
1 Analog Power Current	I_{AVDD}		Pin1		2		mA
2 Digital Power Current	I_{DVDD}		Pin3		1		mA
3 Logic Input Pins G0, G1, SCFS0,S1, ACDC, /RESET			Pin2, 9,12, 13,14, 15,16				
Input High Voltage	V_{IH}	AVDD=5V		2			V
Input Low Voltage	V_{IL}	DVDD=5V				1	V
Input Capacitance	C_{IN}					10	pF
4 Logic Output Pins F1, F2			Pin23, 24				
Output High Voltage	V_{OH1}	$I_H=10mA$		4.4			V
Output Low Voltage	V_{OL1}	$I_L=10mA$				0.5	V
Output Current	I_{O1}				10		mA
5 Logic Output Pins CF, REVP,			Pin22, 20,19				
Output High Voltage	V_{OH2}	$I_H=10mA$		4			V
Output Low Voltage	V_{OL2}	$I_L=10mA$				0.5	V
6 On-chip Reference	V_{ref}	AVDD=5V	Pin10	2.3	2.5	2.7	V
7 Analog Input Pins V1P, V1N V2N, V2P			Pin 5,6, 7,8				
Maximum Input Voltage	V_{AIN}					1	V
DC Input Impedance					330		Kohm

Input Capacitance						10	pF
8 Accuracy							
Measurement Error on Channel 1 and 2							
Gain=1	ENL1	Both Channels with Full-Scale Signal 660mV Over a Dynamic Range 500 to 1	Pin22		0.1	0.4	%
Gain=2	ENL2		Pin22		0.1	0.4	%
Gain=8	ENL8		Pin22		0.1	0.4	%
Gain=16	ENL16		Pin22		0.1	0.4	%
Phase Error between Channels							
Channel 1 Lead 37 (PF=0.8Capacitive)			Pin22		0.1	0.3	%
Channel 1 Lags (PF=0.5Inductive)			Pin22		0.1	0.3	%
9 Start Current	I _{START}	I _b =5A C=3200, cos ϕ =1 Voltage Channel Inputs 110mV Gain of Current Channel 16	Pin5	0.2%I _b			A
10 Positive and Negative Real Power Error (%)	ENP	V _v = 110mV, V(I)= 2mV, cos ϕ =1 V _v = 110mV, V(I)= 2mV, cos ϕ =-1	Pin22			0.4	%
11 Gain Error	Gain error	External 2.5V Reference, Gain=1, V1=V2=500mV DC	Pin22			10	%
12 Gain Error Match			Pin22	0.2		1	%
13 Power Supply Monitor Voltage	V _{down}	Power Supply vary from 3.5V to 5V, and Current Channel with Full-Scale Signal	Pin22	3.9	4	4.1	V

TERMINOLOGY

1) Measurement Error

The error associated with the energy measurement made by the IC is defined by the following formula:

$$\text{Percentage Error} = \frac{\text{Energy Registered} - \text{True Energy}}{\text{True Energy}} \times 100\%$$

2) Nonlinear Error

The Nonlinear Error is defined by the following formula:

$$eNL\% = [(\text{Error at } X - \text{Error at } I_b) / (1 + \text{Error at } I_b)] \times 100\%$$

When $V(v) = 110\text{mV}$, $\cos \phi = 1$, over the range of $5\%I_b$ to $800\%I_b$, the nonlinear error should be less than 0.1% .

3) Positive And Negative Real Power Error

When the positive real power and the negative real power is equal, and $V(v) = 110\text{mV}$, the test current is I_b , then the positive and negative real power error can be achieved by the following formula:

$$eNP\% = [(eN\% - eP\%) / (1 + eP\%)] \times 100\%$$

Where: $eP\%$ is the Positive Real Power Error, $eN\%$ is the Negative Real Power Error.

4) Gain Error

The gain error of the IC is defined as the difference between the measured output frequency (minus the offset) and the ideal output frequency. It is measured with a gain of 1 in channel V1. The difference is expressed as a percentage of the ideal frequency. The ideal frequency is obtained from the IC transfer function.

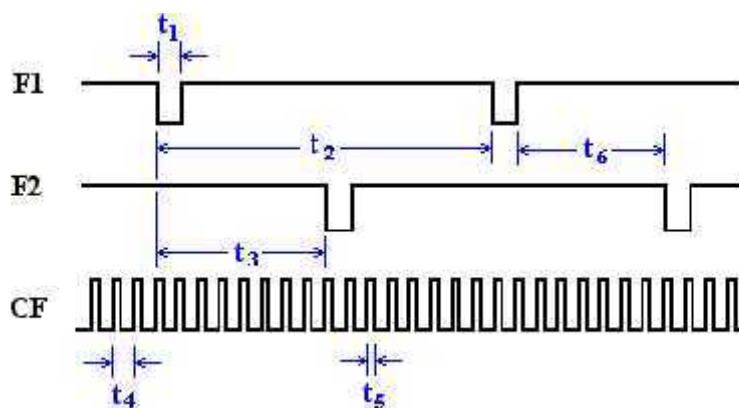
5) Gain Error Match

The gain error match is defined as the gain error (minus the offset) obtained when switching between a gain of 1 and a gain of 2, 8, or 16. It is expressed as a percentage of the output frequency obtained under a gain of 1. This gives the gain error observed when the gain selection is changed from 1 to 2, 8 or 16.

6) Power Supply Monitor

has the on-chip Power Supply monitoring. The will remain in a reset condition until the supply voltage on AVDD reaches 4 V . If the supply falls below 4 V , the will also be reset and no pulses will be issued on F1, F2 and CF.

TIMING CHARACTERISTIC



(AVDD=DVDD=5V, AGND=DGND=0V, On-Chip Reference, CLKIN=3.58MHz, Temperature range: -40~+85 C)

Parameter	Value	Comments
t1	275ms	F1 and F2 pulse-width (Logic Low). When the power is low, the t1 is equal to 275ms; when the power is high, and the output period exceeds 550ms, t1 equals to half of the output period.
t2		F1 or F2 output pulse period.
t3	½ t2	Time between F1 falling edge and F2 falling edge.
t4	90ms	CF pulse-width (Logic high). When the power is low, the t4 is equal to 90ms; when the power is high, and the output period exceeds 180ms, t4 equals to half of the output period.
t5		CF Pulse Period. See Transfer Function section.
t6	CLKIN/4	Minimum Time Between F1 and F2.

Notes:

- 1) CF is not synchronous to F1 or F2 frequency outputs.
- 2) Sample tested during initial release and after any redesign or process change that may affect this parameter.

THEORY OF OPERATION

Principle of Energy Measure

In energy measure, the power information varying with time is calculated by a direct multiplication of the voltage signal and the current signal. Assume that the current signal and the voltage signal are cosine functions; U_{max} , I_{max} are the peak values of the voltage signal and the current signal; ω is the angle frequency of the input signals; the phase difference between the

current signal and the voltage signal is expressed as Φ . Then the power is given as follows:

$$p(t) = U_{max} \cos(\omega t) I_{max} \cos(\omega t - \Phi)$$

If $\Phi = 0$:

$$p(t) = \frac{U_{max} I_{max}}{2} [1 + \cos(2\omega t)]$$

If $\Phi \neq 0$:

$$\begin{aligned}
 p(t) &= U_{max} \cos(\omega t) I_{max} \cos(\omega t - \Phi) \\
 &= U_{max} \cos(\omega t) I_{max} [\cos(\omega t) \cos(\Phi) + \sin(\omega t) \sin(\Phi)] \\
 &= \frac{U_{max} I_{max}}{2} [1 + \cos(2\omega t)] \cos(\Phi) + \frac{U_{max} I_{max}}{2} \cos(\omega t) \sin(\omega t) \sin(\Phi) \\
 &= \frac{U_{max} I_{max}}{2} [1 + \cos(2\omega t)] \cos(\Phi) + \frac{U_{max} I_{max}}{2} \sin(2\omega t) \sin(\Phi) \\
 &= \frac{U_{max} I_{max}}{2} \cos(\Phi) + \frac{U_{max} I_{max}}{2} \cos(2\omega t) \cos(\Phi) + \frac{U_{max} I_{max}}{2} \sin(2\omega t) \sin(\Phi) \\
 &= \frac{U_{max} I_{max}}{2} \cos(\Phi) + \frac{U_{max} I_{max}}{2} \cos(2\omega t) \cos(\Phi) + \frac{U_{max} I_{max}}{2} \sin(2\omega t) \sin(\Phi)
 \end{aligned}$$

$P(t)$ is called as the instantaneous power signal. The ideal $p(t)$ consists of the dc component and ac component whose frequency is 2ω . The dc component is called as the average active power, that

is:

$$P = \frac{U_{\max} I_{\max}}{2} \cos(\phi)$$

The average active power is related to the cosine value of the phase difference between the voltage signal and the current signal. This cosine value is called as Power Factor (PF) of the two channel signals.

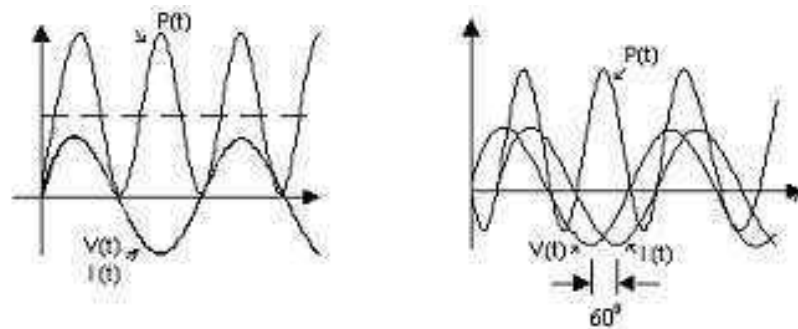


Figure1. The Effect of phase

When the signal phase difference between the voltage and current channels is more than 90° , the average active power is negative. It indicates the user is using the electrical energy reversely.

Operation Process

In IC, the two ADCs digitize the voltage signals from the current and voltage transducers. These ADCs are 16-bit second order sigma-delta with an oversampling rate of 900 kHz. This analog input structure greatly simplifies transducer interfacing by providing a wide dynamic range for direct connection to the transducer and also simplifying the antialiasing filter design. A programmable gain stage in the current channel further facilitates easy transducer interfacing. A high pass filter in the current channel removes any dc component from the current signal. This eliminates any inaccuracies in the real power calculation due to offsets in the voltage or current signals.

The real power calculation is derived from the instantaneous power signal. The instantaneous power signal is generated by a direct multiplication of the current and voltage signals. In order to extract the real power component (i.e., the dc component), the instantaneous power signal is low-pass filtered. Figure 2 illustrates the instantaneous real power signal and shows how the real power information can be extracted by low-pass filtering the instantaneous power signal. This scheme correctly calculates real power for nonsinusoidal current and voltage waveforms at all power factors. All signal processing is carried out in the digital domain for superior stability over temperature and time.

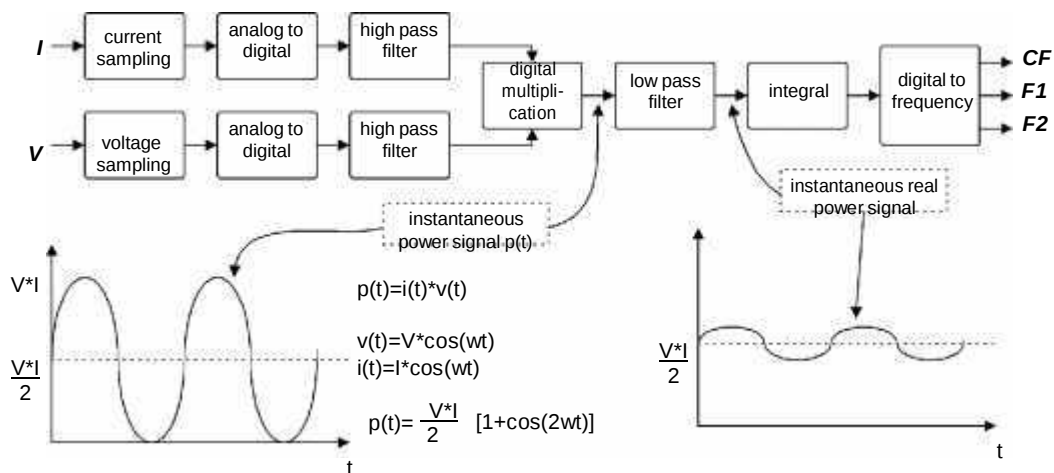


Figure 2. Signal Processing Block Diagram

The low frequency output of the IC is generated by accumulating this real power information. This low frequency inherently means a long accumulation time between output pulses. The output frequency is therefore proportional to the average real power. This average real power information can, in turn, be accumulated (e.g., by a counter) to generate real energy information. Because of its high output frequency and hence shorter integration time, the CF output is proportional to the instantaneous real power. This is useful for system calibration purposes that would take place under steady load conditions.

VOLTAGE CHANNEL INPUT

The output of the line voltage transducer is connected to the IC at this analog input. As Figure 4 shows that channel V2 is a fully differential voltage input. The maximum peak differential signal on Channel 2 is $\pm 660\text{mV}$. Figure 4 illustrates the maximum signal levels that can be connected to the IC Voltage Channel.

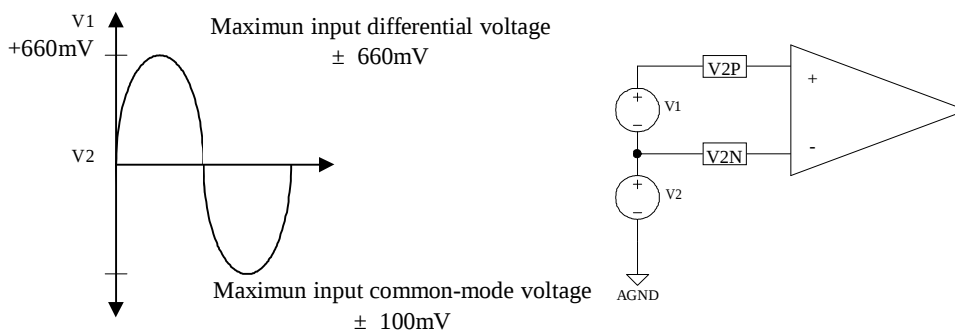


Figure 4. Voltage Channels

Voltage Channel must be driven from a common-mode voltage, i.e., the differential voltage signal on the input must be referenced to a common mode (usually AGND). The analog inputs of the IC can be driven with common-mode voltages of up to 100 mV with respect to AGND. However, best results are achieved using a common mode equal to AGND.

Figure 5 shows two typical connections for Channel V2. The first option uses a PT (potential transformer) to provide complete isolation from the mains voltage. In the second option, the IC is biased around the neutral wire and a resistor divider is used to provide a voltage signal

that is proportional to the line voltage. Adjusting the ratio of R_a and R_b is also a convenient way of carrying out a gain calibration on the meter.

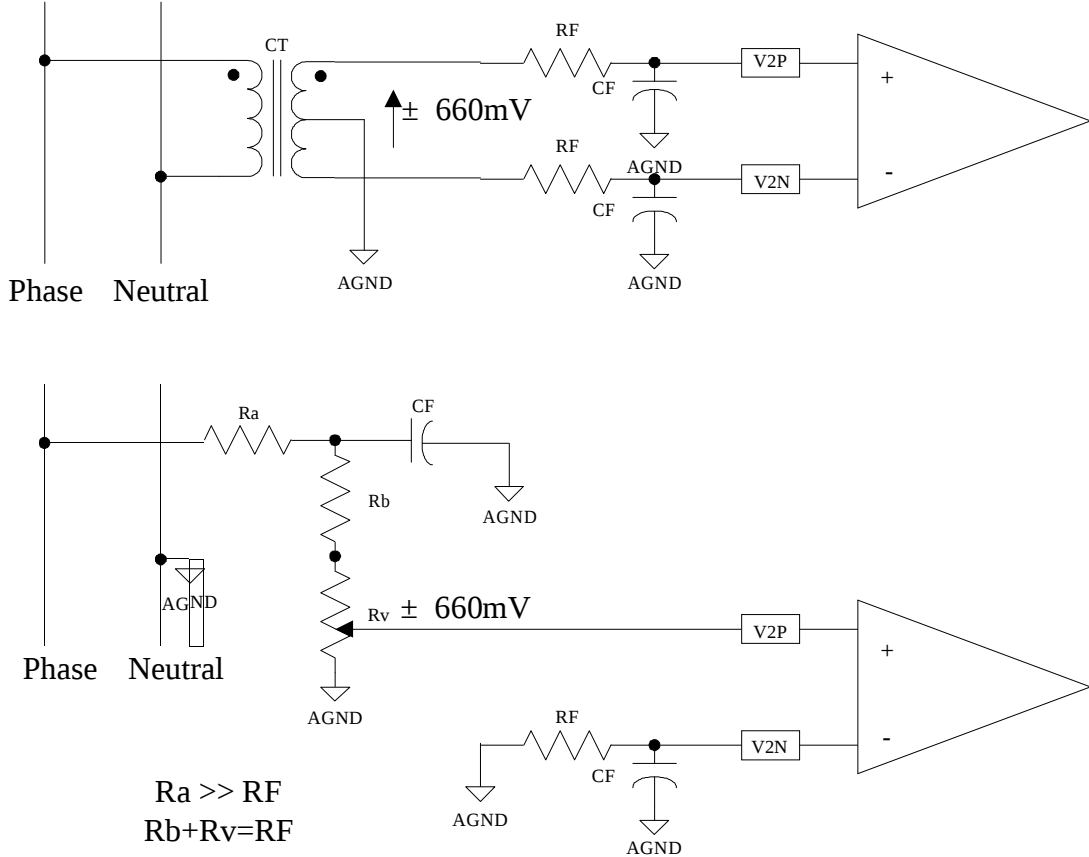


Figure 5. Typical Connections for Voltage Channels

CURRENT CHANNEL INPUT

The voltage outputs from the current transducers are connected to the IC here. The maximum differential voltage on Current Channel 2 is $\pm 660\text{mV}$. The maximum common-mode voltage is $\pm 100\text{mV}$.

Power Supply Monitor

The IC contains an on-chip power supply monitor. If the supply is less than $4\text{V} \pm 5\%$ then the IC will go in an inactive state, i.e. no energy will be accumulated when the supply voltage is below 4V . This is useful to ensure correct device operation at power up and during power down. The power supply monitor has built-in hysteresis and filtering. This gives a high degree of immunity to false triggering due to noisy supplies.

The trigger level is nominally set at 4V , and the tolerance on this trigger level is about $\pm 5\%$. The power supply and decoupling for the part should be such that the ripple at V_{DD} does not exceed $5\text{V} \pm 5\%$ as specified for normal operation.

SLiM technology

The IC adopts the technology of SLiM (Smart Low current Management) to decrease the static power greatly. The static power of IC is about 12mW. It is half of the previous product BL0955 (about 25mW).This technology also decreases the request for power supply design.

BL65XX series products used 0.35um CMOS process. The reliability and consistency are advanced.

OPERATION MODE

Transfer Function

The calculates the product of two voltage signals (on Channel 1 and Channel 2) and then low-pass filters this product to extract real power information. This real power information is then converted to a frequency. The frequency information is output on F1 and F2 in the form of active low pulses. The pulse rate at these outputs is relatively low. It means that the frequency at these outputs is generated from real power information accumulated over a relatively long period of time. The result is an output frequency that is proportional to the average real power. The average of the real power signal is implicit to the digital-to-frequency conversion. The output frequency or pulse rate is related to the input voltage signals by the following equation. (use 3.58MHz oscillator)

$$Freq = \frac{8.34 \cdot V(v) \cdot V(i) \cdot gain \cdot F_z}{V_{REF}^2}$$

Freq——Output frequency on F1 and F2 (Hz) V(v)——

Differential rms voltage signal on Channel 1 (volts) V(i)——

Differential rms voltage signal on Channel 2 (volts)

Gain——1, 2, 8 or 16, depending on the PGA gain selection, using logic inputs G0 and G1

Vref——The reference voltage (2.42 V±8%) (volts)

Fz——One of four possible frequencies selected by using the logic inputs S0 and S1.

S1	S0	Fz(Hz)	XTAL/CLKIN
0	0	1.7	CLKIN/2 ²¹
0	1	3.4	CLKIN/2 ²⁰
1	0	6.8	CLKIN/2 ¹⁹
1	1	13.6	CLKIN/2 ¹⁸

Frequency Output CF

The pulse output CF (Calibration Frequency) is intended for use during calibration. The output pulse rate on CF can be up to 128 times the pulse rate on F1 and F2. The following Table shows how the two frequencies are related, depending on the states of the logic inputs S0, S1 and SCF.

Mode	SCF	S1	S0	CF/F1 (or F2)
1	1	0	0	128
2	0	0	0	64
3	1	0	1	64
4	0	0	1	32
5	1	1	0	32
6	0	1	0	16
7	1	1	1	16
8	0	1	1	2048

Because of its relatively high pulse rate, the frequency at this logic output is proportional to the instantaneous real power. As is the case with F1 and F2, the frequency is derived from the output of the low-pass filter after multiplication. However, because the output frequency is high, this real power information is accumulated over a much shorter time. Hence less averaging is carried out in the digital-to-frequency conversion. With much less averaging of the real power signal, the CF output is much more responsive to power fluctuations.

GAIN SELECTION

By select the digital input G0 and G1 voltage (5V or 0V), we can adjust the gain of current channel. We can see that while increasing the gain, the input dynamic range is decreasing.

G1	G0	Gain	Maximum Differential Signal
0	0	1	660mV
0	1	2	330mV
1	0	8	82mV
1	1	16	41mV

ANALOG INPUT RANGE

The maximum peak differential signal on Voltage Channel is ± 660 mV, and the common-mode voltage is up to 100 mV with respect to AGND.

The analog inputs V1A, V1B, and V1N have the same maximum signal level restrictions as V2P and V2N. However, The Current Channel has a programmable gain amplifier (PGA) with user-selectable gains of 1, 2, 8, or 16. These gains facilitate easy transducer interfacing. The maximum differential voltage is ± 660 mV and the maximum common-mode signal is ± 100 mV.

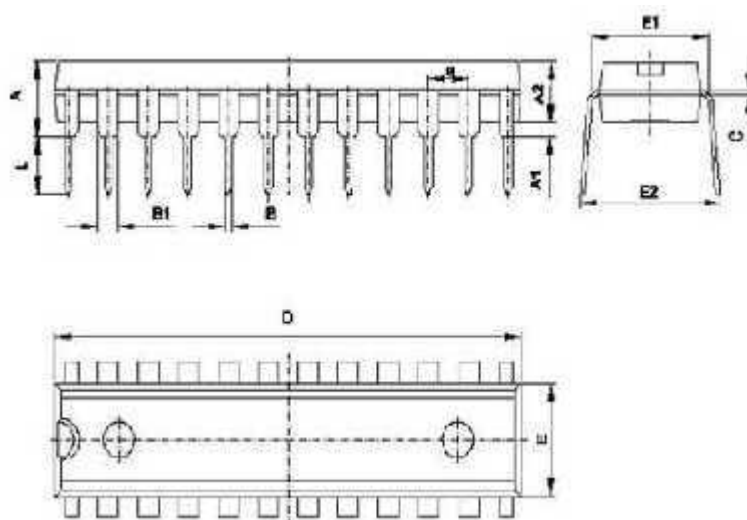
The corresponding Max Frequency of CF/F1/F2 is shown in the following table.

SCF	S1	S0	Fz	Max Frequency of F1, F2 (Hz)		CF Max Frequency (Hz)	
				DC	AC	DC	AC
1	0	0	1.7	0.72	0.36	128 F1,F2=92.16	128 F1,F2=46.08
0	0	0	1.7	0.72	0.36	64 F1,F2=46.08	64 F1,F2=23.04
1	0	1	3.4	1.44	0.72	64 F1,F2=92.16	64 F1,F2=46.08
0	0	1	3.4	1.44	0.72	32 F1,F2=46.08	32 F1,F2=23.04

1	1	0	6.8	2.88	1.44	32 F1,F2=92.16	32 F1,F2=46.08
0	1	0	6.8	2.88	1.44	16 F1,F2=46.08	16 F1,F2=23.04
1	1	1	13.6	5.76	2.88	16 F1,F2=92.16	16 F1,F2=46.08
0	1	1	13.6	5.76	2.88	2048 F1,F2=11.8K	2048 F1,F2=5.9K

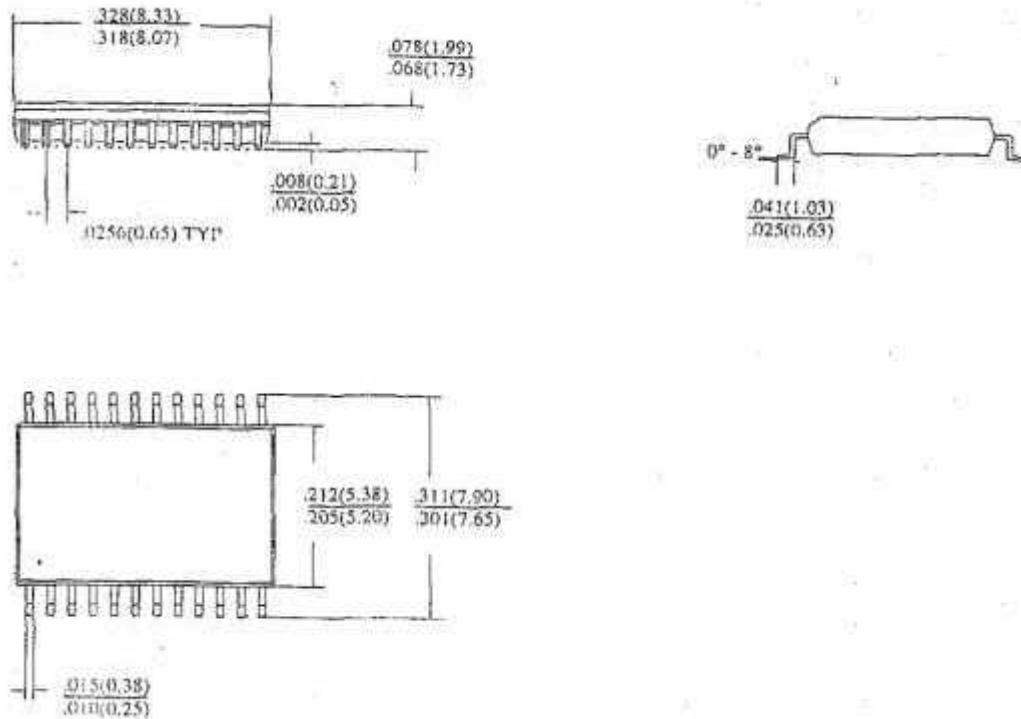
Package Dimensions

1、DIP24



SIGN	SIZE (mm)		SIZE (Inch)	
	MIN	MAX	MIN	MAX
A	3.710	4.310	0.146	0.170
A1	0.510		0.020	
A2	3.200	3.600	0.126	0.142
D	0.300	0.500	0.014	0.022
B1	1.524(TYP)		0.060(TYP)	
C	0.204	0.360	0.008	0.014
D	29.250	29.850	1.152	1.175
E	6.200	6.600	0.244	0.260
E1	7.620(TYP)		0.300(TYP)	
e	2.540(TYP)		0.100(TYP)	
L	3.000	3.600	0.118	0.142
E2	6.200	9.400	0.323	0.370

2、SSOP24



Notice : Sample tested during initial release and after any redesign or process change that may affect parameter. Specification subject to change without notice. Please ask for the newest product specification at any moment.